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TIME-SPACE TRADE-OFFS IN A PEBBLE GAME, (U)
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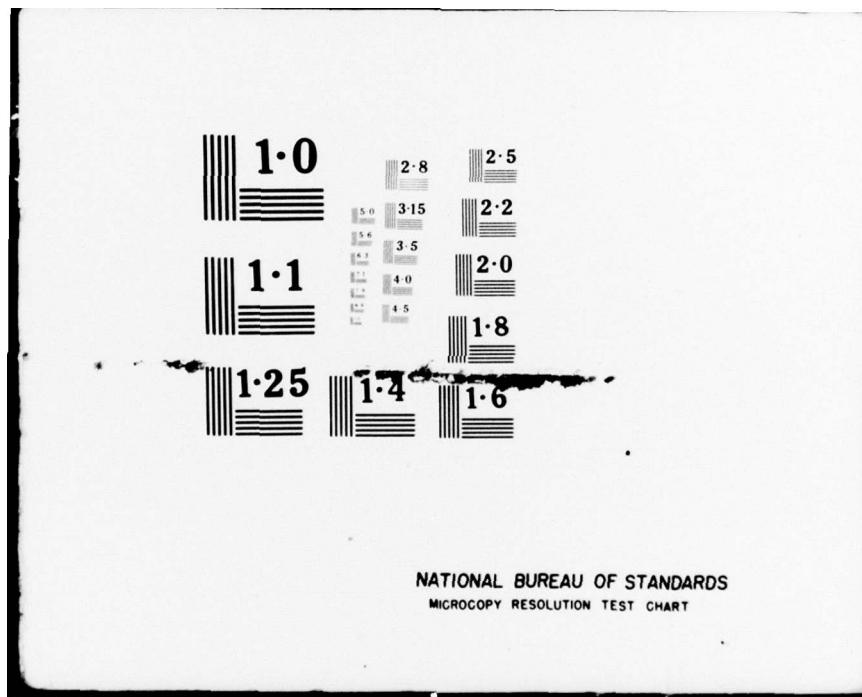
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TIME-SPACE TRADE-OFFS IN A PEBBLE GAME

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Abstract

A certain pebble game on graphs has been studied in various contexts as a model for the time and space requirements of computations [1,2,3,8]. In this note it is shown that there exists a family of directed acyclic graphs G_n and constants c_1, c_2, c_3 such that

- (1) G_n has n nodes and each node in G_n has indegree at most 2.
- (2) Each graph G_n can be pebbled with $c_1\sqrt{n}$ pebbles in n moves.
- (3) Each graph G_n can also be pebbled with $c_2\sqrt{n}$ pebbles, $c_2 < c_1$, but every strategy which achieves this has at least $2^{\frac{c_3}{2}\sqrt{n}}$ moves.

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Let $S(k, n)$ be the set of all directed acyclic graphs with n nodes where each node has indegree at most k . On graphs $G \in S(n, k)$ the following one person game is considered. The game is played by putting pebbles on the nodes of G according to the following rules:

- (i) an input node (i.e., a node without a predecessor) can always be pebbled;
- (ii) if all immediate predecessors of a node c have pebbles one can put a pebble on c ;
- (iii) one can always remove a pebble from a node.

The goal of the game is to put a pebble on some output node (i.e., a node without a successor) of G in such a way that the total number of pebbles which are simultaneously on the graph is minimized.

The game models the time and space requirements of computations in the following sense. The nodes of G correspond to operations and the pebbles correspond to storage locations. If a pebble is on a node this means that the result of the operation to which the node corresponds is stored in some storage location. Thus the rules have the following meaning:

- (i) input data are always accessible;
- (ii) if all operands of an operation are known and stored somewhere, the operation can be carried out and the result be stored in a new location;
- (iii) storage locations can always be freed.

By the rules a single node can be pebbled many times. This corresponds to recomputation of intermediate results.

In particular the game has been used to model time and space of Turing machines [1,2] as well as length and storage requirements for straight line programs [8].

Known results about the pebble game include

- A: Every graph $G \in S(k, n)$ can be pebbled with $c_k n / \log n$ pebbles where the constant c_k depends only on k [2].
- B: There is a constant c and a family of graphs $G_n \in S(2, n)$ such that for infinitely many n , G_n cannot be pebbled with less than $cn / \log n$ pebbles [4].

For more results see [1,3,4,7,8].

By putting pebbles on the nodes of a graph G in topological order (i.e., if there is an edge from node c to node c' , then c is pebbled first) one can pebble each graph $G \in S(k, n)$ with n pebbles and n moves. However the strategy known to achieve $O(n / \log n)$ pebbles on every graph uses exponential time. Thus it is a natural question to ask if there are graphs $G_n \in S(k, n)$ such that every strategy which achieves a minimal number of pebbles requires necessarily exponential time. This is indeed the case.

Theorem. There exists a family of graphs $G_n \in S(2, n)$, $n = 1, 2, \dots$ and constants $c_1, c_2, c_3, c_2 < c_1$ such that for infinitely many n

- (1) G_n can be pebbled with $c_1 \sqrt{n}$ pebbles in n moves.
- (2) G_n can also be pebbled with $c_2 \sqrt{n}$ pebbles.
- (3) Every strategy which pebbles G_n using only $c_2 \sqrt{n}$ pebbles has at least $2^{\frac{c_3 \sqrt{n}}{c_2}}$ moves.

Thus saving only a constant fraction of the pebbles forces the time required to grow from linear to exponential.

Proof of the theorem: As building blocks for the graphs G_n we need certain special graphs. A directed bipartite graph is a graph whose nodes can be partitioned into two disjoint sets N_1, N_2 such that all edges lead from nodes in N_1 to nodes in N_2 . A directed bipartite graph is an $n-i/j$ -expander if $|N_1| = |N_2| = n$ ($|A|$ denotes the cardinality of A) and for all subsets N' of N_2 of size n/i the following holds:

$$|\{c \mid c \in N_1 \text{ and there is an edge from } c \text{ to a node in } N'\}| > n/j.$$

Lemma 1. For n large enough there exist $n-8/2$ -expanders where the indegree of each node in N_2 is exactly 16.

Proof. With every function $f: \{1, \dots, cn\} \rightarrow \{1, \dots, n\}$ we associate a bipartite graph $G_f \in S(c, 2n)$ with n inputs and n outputs in the following way: The inputs and outputs are numbered from 1 to n and if $f(j) = i$ then there is an edge from input i to output $(j \bmod n)$. Different functions may produce the same graph. A function f is bad if there is a set I of $n/2$ inputs and a set O of $n/8$ outputs such that all edges into O come from I . Otherwise the function f is called good. Clearly if f is good G_f is an $n-8/2$ -expander with the desired properties.

In order to prove the existence of a good function we prove that the fraction of bad functions to all such functions tends with growing n to zero [5,6].

There are n^{cn} functions $f: \{1, \dots, cn\} \rightarrow \{1, \dots, n\}$. There are $\binom{n}{n/2} \binom{n}{n/8}$ ways to choose $n/2$ inputs I and $n/8$ outputs O . For every choice of I and O there are $(n/2)^{cn/8} \cdot n^{7cn/8}$ functions f such that f is bad because in G_f all edges into O come from I .

Hence there are at most $\binom{n}{n/2} \binom{n}{n/8} \cdot (n/2)^{cn/8} \cdot n^{7cn/8}$ bad functions.

Thus the fraction we want to estimate is

$$\begin{aligned} & \binom{n}{n/2} \binom{n}{n/8} \cdot (n/2)^{cn/8} \cdot n^{7cn/8} / n^{cn} \\ &= \binom{n}{n/2} \binom{n}{n/8} / 2^{cn/8} = o(1) \quad \text{for } c \geq 16. \quad \square \end{aligned}$$

Let E'_n be an $n-8/2$ -expander as in Lemma 1. Construct E_n from E'_n by replacing for every output node v the 16 incoming edges by a complete binary tree with 16 leaves, identifying v with the root of the tree and the predecessors of v with the leaves. Obviously $E_n \in S(2, 16n)$.

Let $H_{b,d}$ be the graph consisting of d copies of E_b : E_b^1, \dots, E_b^d where for $2 \leq i \leq d$, the input nodes of E_b^i are identified with the output nodes of E_b^{i-1} . Thus $H_{b,d} \in S(2, (15d+1)b)$.

The set of output nodes of E_b^i is called the i -th level. The input nodes of E_b^1 form level 0.

Lemma 2. $H_{b,d}$ can be pebbled with $2b+16$ pebbles and $(15d+1)b$ moves.

Proof. We say level i is full if all nodes of level i have pebbles. The strategy is to fill the levels one after another. Each level is a cut set. Thus once a new level i has been filled all pebbles above level i can be removed. Hence at most $2b$ pebbles have to be kept on two successive levels. In the process of filling level $i+1$ if level i is full, the 16 extra pebbles are used on the trees between the levels. Because all trees are disjoint except for the leaves each node is pebbled exactly once. \square

Lemma 3. $H_{b,d}$ can be pebbled with $4d+2$ pebbles.

Proof. The depth of a node v is the number of edges in the longest path into v . In a graph $G \in S(2,n)$ every node of depth t can be pebbled with $t+2$ pebbles (this follows easily by induction on t).

Every node in $H_{b,d}$ has depth at most $4d$. \square

The crucial point is

Lemma 4. For all $i \in \{0,1,\dots,d\}$ the following statement holds: If C is any configuration of at most $b/8$ pebbles on $H_{b,d}$, N is any subset of level i s.t. $|N| = b/4$, and M is any sequence of moves, which starts in configuration C , never uses more than $b/8$ pebbles, and during the execution of this sequence of moves each node in N has a pebble at least once, then M has at least 2^i moves.

Proof. By induction on i . For $i = 0$ there is nothing to prove.

Suppose the lemma is true for $i-1$. In configuration C at most $b/8$ pebbles are on the graph. Thus for at least $b/8$ of the nodes v in N , no pebble is on v nor anywhere on the tree which joins v with level $i-1$ except possibly on the leaves. Let N' be a subset of these nodes of size $b/8$ and let P be the set of nodes in level $i-1$ which are connected to N' . By construction of $H_{b,d}$, $|P| \geq b/2$. Because none of the nodes in N' nor any node of their trees have pebbles except for the leaves, during the execution of M each node in P must have a pebble at some time (possibly right at the start).

Divide the strategy M into two parts M_1, M_2 at the earliest move such that during M_1 some $b/4$ nodes of P have or have had pebbles and the remaining $b/4$ or more nodes of P have never had a pebble.

For M_1 the hypothesis of the lemma applies; thus M_1 has at least 2^{i-1} moves. Because M_1 leaves at most $b/8$ pebbles on the graph and M_2 also never uses more than $b/8$ pebbles the hypothesis also applies to M_2 . Hence M_2 has at least 2^{i-1} moves too and the lemma follows. \square

Choose b such that $4d+2 \leq b/8$, e.g. $b = 32d+16$. Then any strategy which pebbles any $b/4$ output nodes of $H_{b,d}$ using at most $4d+2$ pebbles has at least 2^d moves. Thus for at least one of these nodes v pebbling v alone with $4d+2$ pebbles must require $2^d/(b/4) \geq 2^{(1-\epsilon)d}$ moves since $b = O(d)$. Now $n = (15d+1)b$ is the number of nodes of $H_{b,d}$. Hence $d = O(\sqrt{n})$ and $b = O(\sqrt{n})$ and the theorem follows. \square

The above construction also yields:

Corollary. There exists a family of graphs $G_n \in S(2,n)$ such that for every $\epsilon > 0$ the following holds: any strategy which pebbles G_n using $n^{1-\epsilon}$ pebbles has more than polynomially many moves.

Proof. Choose $G_n = H_{b,d}$ with $b = n^{1-1/\log \log n}$ and $d = O(n^{1/\log \log n})$. \square

An interesting open problem is: does there exist a family of graphs $G_n \in S(2,n)$, $n = 1, 2, \dots$ such that pebbling the graphs G_n with $O(n/\log n)$ pebbles requires more than polynomially many moves? As a first step toward resolving this question, Pippenger [7] has exhibited a family of graphs which require a non-linear number of moves when pebbled with $O(n/\log n)$ pebbles.

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